

Løysingsforslag

Oppg. 1

a) i) $f(x) = \sin x + x^2$

$$f'(x) = \underline{\underline{\cos x + 2x}}$$

ii) $\int x e^x dx$

Delvi's integrasjon: $\int u v' dx = uv - \int u' v dx$

$$u = x \Rightarrow u' = 1$$

$$v' = e^x \Leftarrow v = e^x$$

$$\int x e^x dx = x e^x - \int 1 \cdot e^x dx = \underline{\underline{x e^x - e^x + C}}$$

$$= e^x (x - 1) + C$$

b) i) $z = 8 e^{-\frac{3\pi}{2} i} = 8 \left(\cos \left(-\frac{3\pi}{2} \right) + i \sin \left(-\frac{3\pi}{2} \right) \right) =$

$$8 \left(\cos \frac{\pi}{2} + i \sin \frac{\pi}{2} \right) = 8(0 + i) = \underline{\underline{8i}}$$

ii) $w = -1 + i = r e^{i\theta}$

$$r^2 = (-1)^2 + 1^2, \quad r = \sqrt{2}$$

$$\tan \theta = \frac{1}{-1} = -1, \quad \theta = \pi - \frac{\pi}{4} = \frac{3\pi}{4}$$

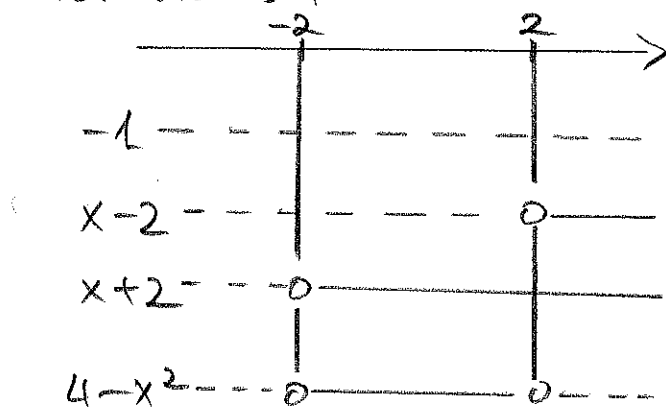
$$w = \sqrt{2} e^{\frac{3\pi}{4} i}$$

$$c) f(x) = \ln(4-x^2) + \frac{1}{\sin x}$$

$$\text{Krev: } 4-x^2 > 0 \text{ og } \sin x \neq 0$$

$$4-x^2 > 0 \Leftrightarrow -(x-2)(x+2) > 0 \Leftrightarrow$$

Førløpsdiagram:



$$\text{Krev: } -2 < x < 2$$

$$\sin x \neq 0 \Leftrightarrow x \neq n\pi, n \in \mathbb{Z}$$

For $x \in (-2, 2)$ er det bare en x -verdi som gir $\sin x = 0$, nemlig $x=0$.

Den naturlige definisjonsmengde blir

$$D_f = \underline{(-2, 2) \setminus \{0\}} = (-2, 0) \cup (0, 2)$$

$$d) i) \lim_{x \rightarrow 1} \frac{x^2-1}{x^2+1} = \frac{1^2-1}{1^2+1} = \underline{0}$$

$$\lim_{x \rightarrow 1} \frac{x-1}{x^2-1} = \lim_{x \rightarrow 1} \frac{x-1}{(x-1)(x+1)} = \lim_{x \rightarrow 1} \frac{1}{x+1} = \frac{1}{1+1} = \underline{\underline{\frac{1}{2}}}$$

$$\lim_{x \rightarrow 1} \frac{\ln x}{\sin(\pi x)}$$

Både teller og nevner går mot 0. Vi bruker L'Hôpital's regel:

$$\begin{aligned} \lim_{x \rightarrow 1} \frac{\ln x}{\sin(\pi x)} &= \lim_{x \rightarrow 1} \frac{(\ln x)'}{(\sin(\pi x))'} = \lim_{x \rightarrow 1} \frac{\frac{1}{x}}{\pi \cos(\pi x)} = \\ \frac{1}{\pi} \lim_{x \rightarrow 1} \frac{1}{x \cos(\pi x)} &= \frac{1}{\pi} \cdot \frac{1}{1 \cdot \cos \pi} = \underline{\underline{-\frac{1}{\pi}}} \end{aligned}$$

Oppg. 2

$$f(x) = e^{\sqrt{3}x} \sin x$$

- Skal finne alle globale ekstremalpunkt på $[0, \pi]$. Siden f og $f'(x)$ er kontinuerlige, vil disse punktene være randpunkt eller punkt der $f'(x) = 0$

$$\begin{aligned} f'(x) &= \sqrt{3} e^{\sqrt{3}x} \sin x + e^{\sqrt{3}x} \cos x = \\ &e^{\sqrt{3}x} (\sqrt{3} \sin x + \cos x) \end{aligned}$$

Nullpunkt for $f'(x)$:

$$f'(x) = 0$$

$$e^{\sqrt{3}x} (\sqrt{3} \sin x + \cos x) = 0$$

$$\sqrt{3} \sin x + \cos x = 0$$

$$\sqrt{3} \frac{\sin x}{\cos x} + 1 = 0$$

$$\tan x = -\frac{1}{\sqrt{3}}$$

$$x = \pi - \frac{\pi}{6} + n\pi = \frac{5\pi}{6} + n\pi, \quad n \in \mathbb{Z}$$

$$\text{For } x \in [0, \pi]: x = \frac{5\pi}{6}$$

Funktionsvärden:

$$f(0) = e^{\sqrt{3} \cdot 0} \sin 0 = 0$$

$$f\left(\frac{5\pi}{6}\right) = e^{\sqrt{3} \cdot \frac{5\pi}{6}} \sin \frac{5\pi}{6} = \frac{1}{2} e^{\sqrt{3} \cdot \frac{5\pi}{6}}$$

$$f(\pi) = e^{\sqrt{3} \cdot \pi} \sin \pi = 0$$

Alltså är randpunkterna, $(0, 0)$ och $(\pi, 0)$,
globala minima, medan $\left(\frac{5\pi}{6}, \frac{1}{2} e^{\sqrt{3} \cdot \frac{5\pi}{6}}\right)$ är
globalt maximum.

Oppg. 3

$$a) \quad y' = y + 5e^x \Leftrightarrow y' - y = 5e^x$$

Integrerande faktor: $e^{F(x)}$ der $F'(x) = -1$
Vel $F = -x$.

$$e^{-x} (y' - y) = e^{-x} \cdot 5e^x = 5$$

$$(e^{-x} y)' = 5$$

$$e^{-x} y = \int 5 dx = 5x + C$$

$$\underline{y = e^x (5x + C)}$$

(b)

$$y'' - y = x, \quad y(0) = y'(0) = 1$$

- Løser først homogen ligning:

$$y'' - y = 0$$

- Går ut fra at $y = e^{rx}$ slik at
 $y'' = r^2 e^{rx}$:

$$r^2 e^{rx} - e^{rx} = 0$$

$$r^2 - 1 = 0, \quad r = \pm 1$$

Generell løsning:

$$y_h = A e^x + B e^{-x}$$

- Går ut fra at vi kan finne en
partikulær løsning på forma

$$y_p = ax + b$$

$$y_p' = a, \quad y_p'' = 0$$

Set inn:

$$0 - (ax + b) = x, \quad -ax - b = 1x + 0$$

$$-a = 1 \quad \text{og} \quad -b = 0,$$

$$a = -1 \quad \text{og} \quad b = 0$$

$$y_p = -x$$

Generell løsning: $y = y_h + y_p = A e^x + B e^{-x} - x$

Initialbetingelse: $y(0)=1$

$$A \cdot 1 + B \cdot 1 - 0 = 1, \quad A + B = 1$$

$$y' = A e^x - B e^{-x} - 1$$

Initialbetingelse: $y'(0)=1$

$$A \cdot 1 - B \cdot 1 - 1 = 1, \quad A - B = 2$$

$$\begin{cases} A + B = 1 \\ A - B = 2 \end{cases} \Leftrightarrow \begin{cases} 2A = 3 \\ 2B = -1 \end{cases} \Leftrightarrow \begin{cases} A = \frac{3}{2} \\ B = -\frac{1}{2} \end{cases}$$

Løsning:

$$\underline{\underline{y(x) = \frac{3}{2} e^x - \frac{1}{2} e^{-x} - x}}$$

c) $(x^2+1)y' = \sqrt{y}, \quad y(0)=4$

$$\frac{1}{\sqrt{y}} \frac{dy}{dx} = \frac{1}{x^2+1}$$

$$\frac{1}{\sqrt{y}} dy = \frac{dx}{x^2+1}$$

$$\int y^{-1/2} dy = \int \frac{1}{x^2+1} dx$$

$$\frac{1}{-\frac{1}{2}+1} y^{-1/2+1} = \arctan x + C'$$

$$2\sqrt{y} = \arctan x + C'$$

Initialbetingelse: $y(0)=4$

$$2\sqrt{4} = \arctan 0 + C', \quad C' = 2\sqrt{4} = 4$$

NB!

Denne udgør!

Altså:

$$2\sqrt{y} = \arctan x + 4$$

$$\sqrt{y} = \frac{1}{2} \arctan x + 2$$

$$\underline{\underline{y = \left(\frac{1}{2} \arctan x + 2\right)^2}}$$

Oppg. 4

$$A = \begin{bmatrix} 0 & 4 & 2 \\ 0 & 2 & 2 \\ 1 & 4 & 6 \end{bmatrix}, \quad B = \begin{bmatrix} 2 & 0 \\ 3 & 0 \\ 1 & 1 \end{bmatrix}$$

a) Dersom A er invertibel, er matrisen $[A | I_3]$ relle-ekvivalent med $[I_3 | A^{-1}]$.

$$[A | I_3] = \begin{bmatrix} 0 & 4 & 2 & 1 & 0 & 0 \\ 0 & 2 & 2 & 0 & 1 & 0 \\ 1 & 4 & 6 & 0 & 0 & 1 \end{bmatrix} \begin{matrix} \leftarrow \\ -2 \cdot 2 \leftarrow \frac{1}{2} \\ \leftarrow \end{matrix} \sim$$

$$\begin{bmatrix} 0 & 0 & -2 & 1 & -2 & 0 \\ 0 & 1 & 1 & 0 & \frac{1}{2} & 0 \\ 1 & 0 & 2 & 0 & -2 & 1 \end{bmatrix} \begin{matrix} \leftarrow \leftarrow \\ \leftarrow \leftarrow \\ \leftarrow \leftarrow \end{matrix} \sim$$

$$\begin{bmatrix} 1 & 0 & 0 & 1 & -4 & 1 \\ 0 & 1 & 1 & 0 & \frac{1}{2} & 0 \\ 0 & 0 & -2 & 1 & -2 & 0 \end{bmatrix} \leftarrow -\frac{1}{2} \sim \begin{bmatrix} 1 & 0 & 0 & 1 & -4 & 1 \\ 0 & 1 & 1 & 0 & \frac{1}{2} & 0 \\ 0 & 0 & 1 & -\frac{1}{2} & 1 & 0 \end{bmatrix} \begin{matrix} \leftarrow \\ \leftarrow \\ -1 \sim \end{matrix}$$

$$\begin{bmatrix} 1 & 0 & 0 & 1 & -4 & 1 \\ 0 & 1 & 0 & \frac{1}{2} & -\frac{1}{2} & 0 \\ 0 & 0 & 1 & -\frac{1}{2} & 1 & 0 \end{bmatrix} = [I_3 | A^{-1}]$$

$$\text{Alternativ: } A^{-1} = \underline{\underline{\begin{bmatrix} 1 & -4 & 1 \\ \frac{1}{2} & -\frac{1}{2} & 0 \\ -\frac{1}{2} & 1 & 0 \end{bmatrix}}}$$

$$\text{Kontroll: } A^{-1}A = \begin{bmatrix} 1 & -4 & 1 \\ \frac{1}{2} & -\frac{1}{2} & 0 \\ -\frac{1}{2} & 1 & 0 \end{bmatrix} \begin{bmatrix} 0 & 4 & 2 \\ 0 & 2 & 2 \\ 1 & 4 & 6 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

OK

$$AB = \begin{bmatrix} 0 & 4 & 2 \\ 0 & 2 & 2 \\ 1 & 4 & 6 \end{bmatrix} \begin{bmatrix} 2 & 0 \\ 3 & 0 \\ 1 & 1 \end{bmatrix} =$$

$$\begin{bmatrix} 0 \cdot 2 + 4 \cdot 3 + 2 \cdot 1 & 0 \cdot 0 + 4 \cdot 0 + 2 \cdot 1 \\ 0 \cdot 2 + 2 \cdot 3 + 2 \cdot 1 & 0 \cdot 0 + 2 \cdot 0 + 2 \cdot 1 \\ 1 \cdot 2 + 4 \cdot 3 + 6 \cdot 1 & 1 \cdot 0 + 4 \cdot 0 + 6 \cdot 1 \end{bmatrix} = \underline{\underline{\begin{bmatrix} 14 & 2 \\ 8 & 2 \\ 20 & 6 \end{bmatrix}}}$$

B har 2 søyler, og A har 3 rader.
Derfor er ikke BA definert.

b) Vi kjenner at vektorane som søylene i A . Vi har, ved å finne A^{-1} , vist at A er invertibel.

Difor er søylene i A , og også dei gitte vektorane, lineært uavhengige.

c) Løningssystemet $A\vec{x} = \vec{b}$, med A kvadratisk, har eindeleg løysing hvis og berre hvis det $A \neq 0$.

Vi rekner ut determinanten til koeffisientmatrisa:

$$\begin{vmatrix} 4 & 0 & 0 \\ 2 & k & 6 \\ 4 & 1 & k-1 \end{vmatrix} = 4 \begin{vmatrix} k & 6 \\ 1 & k-1 \end{vmatrix} = 4(k(k-1) - 6 \cdot 1) =$$

$$4(k^2 - k - 6)$$

Krever at denne skal vere ulik 0:

$$4(k^2 - k - 6) \neq 0 \Leftrightarrow k \neq \frac{-(-1) \pm \sqrt{(-1)^2 - 4 \cdot 1 \cdot (-6)}}{2}$$

$$k \neq \frac{1 \pm 5}{2}, \quad k \neq \frac{1-5}{2} = -2 \wedge k \neq \frac{1+5}{2} = 3$$

Vi har eindeleg løysing for $k \notin \{-2, 3\}$.

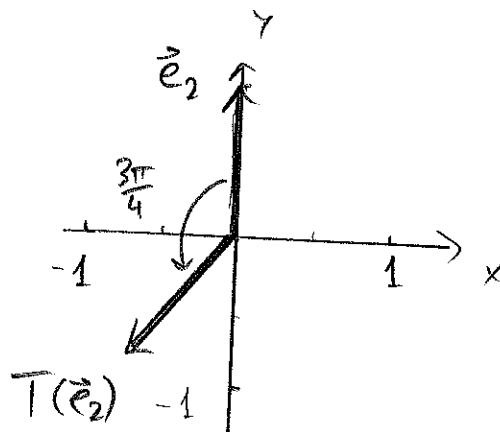
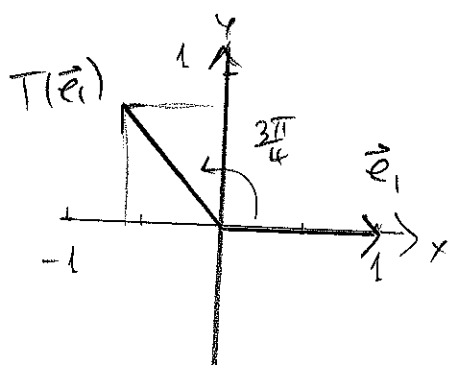
d) $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$

-Rotation $\frac{3\pi}{4}$ mot klokke

$$T(\vec{x}) = A \vec{x}$$

der standardmatrisen $A = [T(\vec{e}_1) \mid T(\vec{e}_2)]$

$$\vec{e}_1 = \begin{bmatrix} 1 \\ 0 \end{bmatrix} \text{ og } \vec{e}_2 = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$



Av figurene ser vi at

$$T(\vec{e}_1) = \begin{bmatrix} \cos \frac{3\pi}{4} \\ \sin \frac{3\pi}{4} \end{bmatrix} = \begin{bmatrix} -\cos \frac{\pi}{4} \\ \sin \frac{\pi}{4} \end{bmatrix} = \begin{bmatrix} -\frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{bmatrix}$$

og at

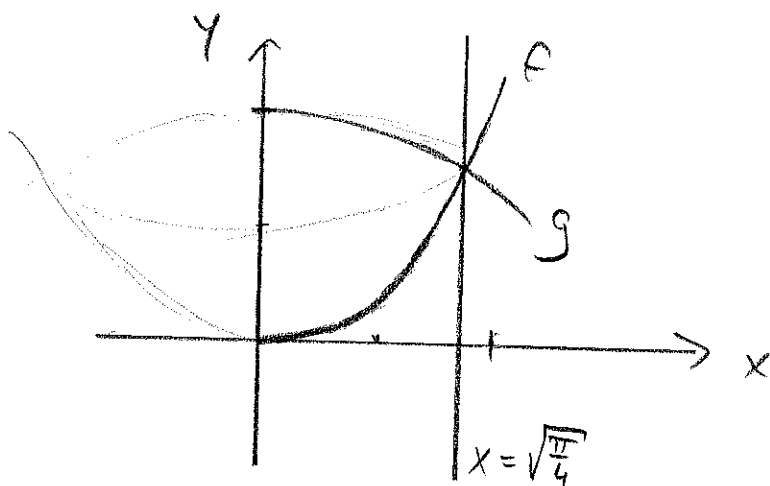
$$T(\vec{e}_2) = \begin{bmatrix} -\sin \frac{3\pi}{4} \\ \cos \frac{3\pi}{4} \end{bmatrix} = \begin{bmatrix} -\sin \frac{\pi}{4} \\ -\cos \frac{\pi}{4} \end{bmatrix} = \begin{bmatrix} -\frac{1}{\sqrt{2}} \\ -\frac{1}{\sqrt{2}} \end{bmatrix}$$

Vi får

$$A = \begin{bmatrix} -\frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} \end{bmatrix}$$

Oppg. 5

$$f(x) = \sin x^2, \quad g(x) = \cos x^2$$



Volum av omdreingslegem:

$$V = 2\pi \int_0^{\sqrt{\pi/4}} x (g(x) - f(x)) dx =$$

$$2\pi \int_0^{\sqrt{\pi/4}} x (\cos x^2 - \sin x^2) dx$$

Variablebyte:

$$u = x^2, \quad \frac{du}{dx} = 2x, \quad dx = \frac{1}{2x} du$$

$$u(0) = 0, \quad u(\sqrt{\pi/4}) = \frac{\pi}{4}$$

$$V = 2\pi \int_0^{\pi/4} x (\cos u - \sin u) \frac{1}{2x} du =$$

$$\pi \int_0^{\pi/4} (\cos u - \sin u) du = \pi [\sin u + \cos u]_0^{\pi/4} =$$

$$\pi (\sin \frac{\pi}{4} + \cos \frac{\pi}{4} - (\sin 0 + \cos 0)) =$$

$$\pi (\frac{\sqrt{2}}{2} + \frac{\sqrt{2}}{2} - 1) = \underline{\underline{\pi (\sqrt{2} - 1)}}$$

Oppg. 6

$$a) \quad M = \begin{bmatrix} -4 & 0 & 0 \\ 3 & -2 & 0 \\ 1 & 2 & 0 \end{bmatrix}$$

$M = P D P^{-1}$ der P har egenvektorene for M som søyler og der tilsvarende egenverdier står langs diagonalen i diagonalmatrisen D .

Eigen v.

$$M \vec{x} = \lambda \vec{x} \Leftrightarrow (M - \lambda I) \vec{x} = \vec{0}$$

Ikkje-trivielle løsninger:

$$\det(M - \lambda I) = 0 \Leftrightarrow$$

$$\begin{vmatrix} -4-\lambda & 0 & 0 \\ 3 & -2-\lambda & 0 \\ 1 & 2 & -\lambda \end{vmatrix} = (-4-\lambda)(-\lambda)(-\lambda) = 0$$

$$\begin{bmatrix} 1 & 2 & 4 \\ 0 & 1 & 3 \\ 0 & 0 & 0 \end{bmatrix} \xleftarrow{-2} \begin{bmatrix} 1 & 0 & -2 \\ 0 & 1 & 3 \\ 0 & 0 & 0 \end{bmatrix}$$

$$x_1 - 2x_3 = 0 \Leftrightarrow x_1 = 2x_3$$

$$x_2 + 3x_3 = 0 \Leftrightarrow x_2 = -3x_3$$

$$\vec{x} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 2x_3 \\ -3x_3 \\ x_3 \end{bmatrix} = x_3 \begin{bmatrix} 2 \\ -3 \\ 1 \end{bmatrix}$$

- Väl $x_3 = 1$ og får egenvektoren $\vec{x}_1 = \begin{bmatrix} 2 \\ -3 \\ 1 \end{bmatrix}$

Eigenvektor for $\lambda_2 = -2$

$$A - (-2)I = \begin{bmatrix} -2 & 0 & 0 \\ 3 & 0 & 0 \\ 1 & 2 & 2 \end{bmatrix} \xrightarrow{\frac{3}{2} \quad \frac{1}{2} \leftarrow -\frac{1}{2}} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 2 & 2 \end{bmatrix} \xleftarrow{\frac{1}{2}}$$

$$\sim \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \end{bmatrix}$$

$$x_1 = 0$$

$$x_2 + x_3 = 0, \quad x_2 = -x_3$$

$$\vec{x} = \begin{bmatrix} 0 \\ x_3 \\ -x_3 \end{bmatrix} = x_3 \begin{bmatrix} 0 \\ 1 \\ -1 \end{bmatrix}$$

Väl $x_3 = 1$ og får egenvektoren $\vec{x}_2 = \begin{bmatrix} 0 \\ 1 \\ -1 \end{bmatrix}$

$$b) N_A' = -4 N_A$$

$$\frac{dN_A}{dt} = -4 N_A$$

$$\frac{dN_A}{N_A} = -4 dt$$

$$\int \frac{1}{N_A} dN_A = \int -4 dt$$

$$\ln |N_A| = -4t + C_1$$

$$|N_A| = e^{-4t + C_1} = e^{C_1} \cdot e^{-4t}$$

$$N_A = \pm e^{C_1} e^{-4t}$$

$$\text{Med } C' = \pm e^{C_1}$$

$$\underline{\underline{N_A(t) = C' e^{-4t}}}$$

$$\text{Skol ha: } N_A(t + T_{1/2}) = \frac{1}{2} N(t)$$

$$C' e^{-4 \cdot (t + T_{1/2})} = \frac{1}{2} \cdot C' e^{-4t}$$

$$e^{-4 \cdot t} \cdot e^{-4 \cdot T_{1/2}} = e^{-4t} \cdot \frac{1}{2}$$

$$e^{-4T_{1/2}} = \frac{1}{2}$$

$$-4T_{1/2} = \ln \frac{1}{2} = \ln 2^{-1} = -\ln 2$$

$$T_{1/2} = \frac{-\ln 2}{-4} = \underline{\underline{\frac{\ln 2}{4}}} \quad (\text{g. e.d.})$$

$$c) \vec{N}'(t) = M \cdot \vec{N}(t)$$

Generell løsning:

$$\vec{N}(t) = C_1 e^{\lambda_1 t} \vec{x}_1 + C_2 e^{\lambda_2 t} \vec{x}_2 + C_3 e^{\lambda_3 t} \vec{x}_3$$

der λ_i og $\vec{x}_i$ er egenverdier og
-vektorerne fra a).

Altså:

$$\vec{N}(t) = C_1 e^{-4t} \begin{bmatrix} 2 \\ -3 \\ 1 \end{bmatrix} + C_2 e^{-2t} \begin{bmatrix} 0 \\ 1 \\ -1 \end{bmatrix} + C_3 \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$$

$$\text{Initialbetingelser: } \vec{N}(0) = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$$

$$C_1 \begin{bmatrix} 2 \\ -3 \\ 1 \end{bmatrix} + C_2 \begin{bmatrix} 0 \\ 1 \\ -1 \end{bmatrix} + C_3 \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$$

$$P \begin{bmatrix} C_1 \\ C_2 \\ C_3 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$$

Totalmatrise:

$$\begin{bmatrix} 2 & 0 & 0 & 1 \\ -3 & 1 & 0 & 0 \\ 1 & -1 & 1 & 0 \end{bmatrix} \xleftarrow{\frac{1}{2}} \begin{bmatrix} 1 & 0 & 0 & \frac{1}{2} \\ -3 & 1 & 0 & 0 \\ 1 & -1 & 1 & 0 \end{bmatrix} \xrightarrow{\substack{R_2 + 3R_1 \\ R_3 - R_1}} \begin{bmatrix} 1 & 0 & 0 & \frac{1}{2} \\ 0 & 1 & 0 & \frac{3}{2} \\ 0 & -1 & 1 & -\frac{1}{2} \end{bmatrix} \xrightarrow{R_3 + R_2} \begin{bmatrix} 1 & 0 & 0 & \frac{1}{2} \\ 0 & 1 & 0 & \frac{3}{2} \\ 0 & 0 & 1 & 1 \end{bmatrix}$$

Vi får

$$G_1 = \frac{1}{2}, G_2 = \frac{3}{2} \text{ og } G_3 = 1$$

Slår at

$$\vec{N}(t) = \begin{bmatrix} N_A(t) \\ N_B(t) \\ N_C(t) \end{bmatrix} = \frac{1}{2} e^{-4t} \begin{bmatrix} 2 \\ -3 \\ 1 \end{bmatrix} + \frac{3}{2} e^{-2t} \begin{bmatrix} 0 \\ 1 \\ -1 \end{bmatrix} + \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$$

d) Vi legger sammen S : $S' = N_A(t) + N_B(t) + N_C(t)$

Løysing fra c gir at

$$N_A(t) = \frac{1}{2} e^{-4t} \cdot 2 = e^{-4t}$$

$$N_B(t) = \frac{1}{2} e^{-4t} \cdot (-3) + \frac{3}{2} e^{-2t} \cdot 1 = \frac{3}{2} (e^{-2t} - e^{-4t})$$

$$N_C(t) = \frac{1}{2} e^{-4t} \cdot 1 + \frac{3}{2} e^{-2t} \cdot (-1) + 1 = \\ \frac{1}{2} e^{-4t} - \frac{3}{2} e^{-2t} + 1$$

Sum:

$$S = N_A + N_B + N_C = e^{-4t} + \frac{3}{2} (e^{-2t} - e^{-4t}) + \\ \frac{1}{2} e^{-4t} - \frac{3}{2} e^{-2t} + 1 =$$

$$e^{-4t} (1 - \frac{3}{2} + \frac{1}{2}) + e^{-2t} (\frac{3}{2} - \frac{3}{2}) + 1 = 1$$

Altså: $S = 1$ hele tida.

Alternativt kan vi bruke differensial-
likninga til å bestemme $S'(t)$:

$$\vec{N}' = M \vec{N}$$

$$\begin{bmatrix} N_A' \\ N_B' \\ N_C' \end{bmatrix} = \begin{bmatrix} -4 & 0 & 0 \\ 3 & -2 & 0 \\ 1 & 2 & 0 \end{bmatrix} \begin{bmatrix} N_A \\ N_B \\ N_C \end{bmatrix} = \begin{bmatrix} -4N_A \\ 3N_A - 2N_B \\ N_A + 2N_B \end{bmatrix}$$

$$S'(t) = N_A'(t) + N_B'(t) + N_C'(t) =$$

$$-4N_A + 3N_A - 2N_B + N_A + 2N_B = 0$$

$S'(t) = 0 \Leftrightarrow S$ endrer seg ikke med
tiden t .

Vi kan også løse likningssystemet i c) utan å diagonalisere; det er ikke egentleg løp. Vi skriv likningane ut komponentvis:

$$N_A' = -4N_A \quad (i)$$

$$N_B' = 3N_A - 2N_B \quad (ii)$$

$$N_C' = N_A + 2N_B \quad (iii)$$

(i) har vi alt løyst og fått

$$N_A = C e^{-4t}. \text{ Siden } N_A(0) = 1, \text{ må vi ha } C = 1$$

$$\text{Alt så: } N_A = e^{-4t}$$

$$N_B' = 3 \cdot e^{-4t} - 2N_B$$

$$N_B' + 2N_B = 3e^{-4t}$$

Integrerende faktor: e^{2t}

$$e^{2t}(N_B' + 2N_B) = e^{2t} \cdot 3e^{-4t} = 3e^{-2t}$$

$$(e^{2t} N_B)' = 3e^{-2t}$$

$$e^{2t} N_B = \int 3e^{-2t} dt = -\frac{3}{2} e^{-2t} + D$$

$$N_B = e^{-2t} \left(-\frac{3}{2} e^{-2t} + D \right) = -\frac{3}{2} e^{-4t} + D e^{-2t}$$

Initialbetingelse: $N_B(0) = 0$

$$-\frac{3}{2} e^0 + D e^0 = 0, \quad D = \frac{3}{2}$$

Ans:

$$N_B = -\frac{3}{2}e^{-4t} + \frac{3}{2}e^{-2t} = \frac{3}{2}(e^{-2t} - e^{-4t})$$

Løsning (iii) løser vi ved rein integrasjon:

$$N'_C = N_A + 2N_B = e^{-4t} + 2 \cdot \frac{3}{2}(e^{-2t} - e^{-4t}) = e^{-4t} + 3e^{-2t} - 3e^{-4t} = 3e^{-2t} - 2e^{-4t}$$

$$N_C = \int N'_C(t) dt = \int (3e^{-2t} - 2e^{-4t}) dt = -\frac{3}{2}e^{-2t} - \frac{2}{-4}e^{-4t} + E =$$

$$-\frac{3}{2}e^{-2t} + \frac{1}{2}e^{-4t} + E$$

Initialbetingelse: $N_C(0) = 0$

$$\frac{1}{2} \cdot 1 - \frac{3}{2} \cdot 1 + E = 0, \quad E = 1$$

Vi får:

$$N_A(t) = e^{-4t}$$

$$N_B(t) = \frac{3}{2}(e^{-2t} - e^{-4t})$$

$$N_C(t) = \frac{1}{2}e^{-4t} - \frac{3}{2}e^{-2t} + 1$$

Eller:

$$\vec{N}(t) = \begin{bmatrix} e^{-4t} \\ \frac{3}{2}(e^{-2t} - e^{-4t}) \\ \frac{1}{2}e^{-4t} - \frac{3}{2}e^{-2t} + 1 \end{bmatrix} = \frac{1}{2}e^{-4t} \begin{bmatrix} 2 \\ -3 \\ 1 \end{bmatrix} + \frac{3}{2}e^{-2t} \begin{bmatrix} 0 \\ 1 \\ -1 \end{bmatrix} + \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$$